

# How to trade large block of shares?

## Introduction to optimal execution strategies

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# Introduction

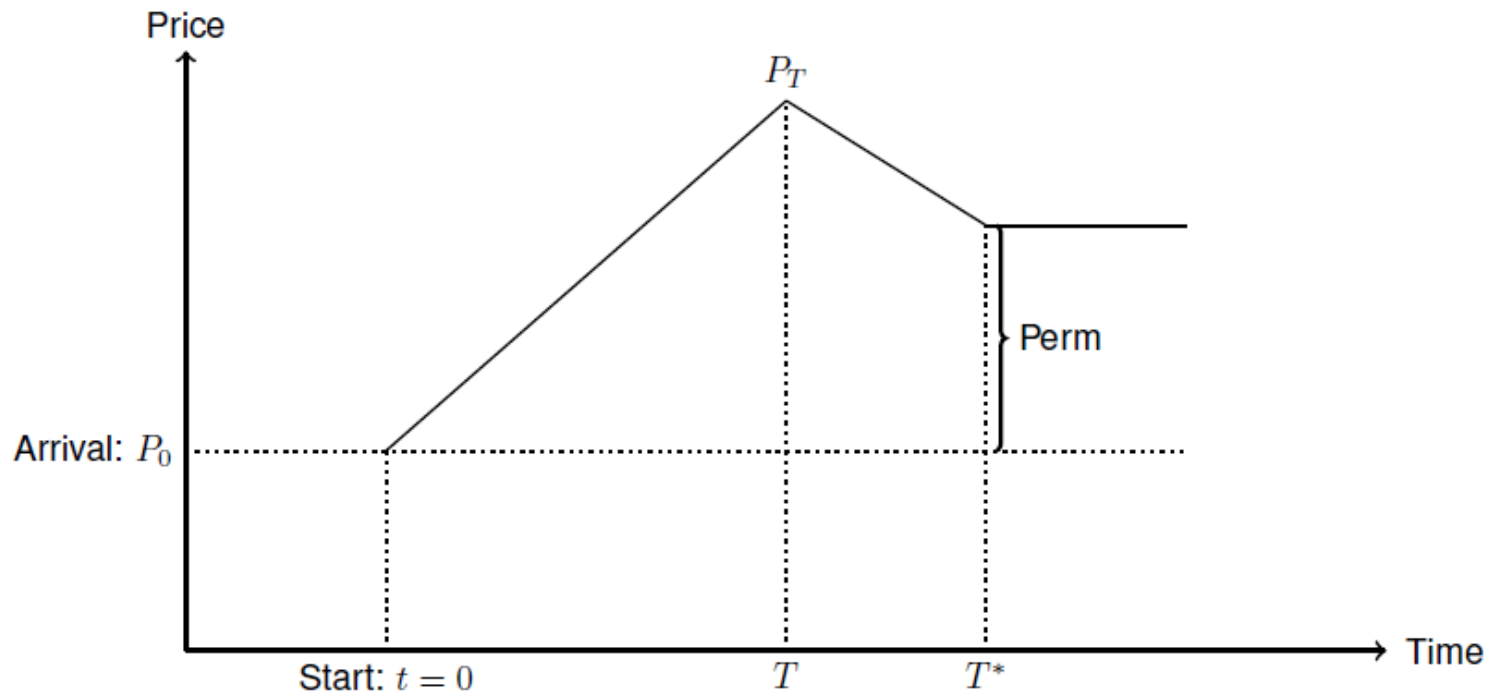
- We consider the problem of unwinding a single-stock portfolio with position  $q_0 > 0$  over the time interval  $[0, T]$ .
- The trader's position is modeled by the process  $(q_t)_{t \in [0, T]}$  with the dynamics

$$dq_t = v_t dt$$

where  $\mathbf{v} = (v_t)_{t \in [0, T]}$  satisfies the unwinding constraint  $\int_0^T v_t dt = -q_0$ .

# Permanent vs instantaneous (temporary) market impact

It is customary to decompose market impact costs of a trade into its permanent and temporary constituent parts



## Normal dynamics vs. log-normal dynamics

We denote by  $\mathcal{A}$  the set of admissible controls  $\mathbf{v}$ .

The mid-price of the stock is modeled by the process  $(S_t)_{t \in [0, T]}$ , where

$$S_t = S_t^{\text{mid}} = \frac{1}{2} \cdot (S_t^{\text{bid}} + S_t^{\text{ask}})$$

$$dS_t = \sigma dW_t + kv_t dt$$

$\sigma$  - the arithmetic volatility

$k \geq 0$  - the magnitude of the permanent market impact

## Execution costs & cash account process

- Let introduce the market volume process  $(V_t)_{t \in [0, T]}$ , which represents the velocity of the volume traded by other agents (it does not take into account our own trades). We assume that it is a deterministic, continuous, positive, and bounded process.
- The price obtained by the trader for each share at time  $t$  is of the form  $S_t + g\left(\frac{v_t}{V_t}\right)$ , where  $g$  is an increasing function satisfying  $g(0) = 0$ . It models the instantaneous market impact.
- $L(\rho) = \rho g(\rho)$  - execution cost function
- We denote by  $(X_t)_t$  the cash account process modeling the amount of cash on the trader's account. It's dynamics is given by

$$dX_t = -v_t \left( S_t + g\left(\frac{v_t}{V_t}\right) \right) dt = -v_t S_t dt - V_t L\left(\frac{v_t}{V_t}\right) dt$$

## Assumptions on the function $L: \mathbb{R} \rightarrow \mathbb{R}$

The assumptions on the function  $L: \mathbb{R} \rightarrow \mathbb{R}$  are the following:

- No fixed cost, i.e.,  $L(0) = 0$ ,
- $L$  is strictly convex, increasing on  $\mathbb{R}_+$  and decreasing on  $\mathbb{R}_-$ ,
- $L$  is asymptotically super-linear, i.e.,  $\lim_{|\rho| \rightarrow \infty} \frac{L(\rho)}{|\rho|} = +\infty$ .

In practical examples

$$L(\rho) = |\rho|^{1+\phi} \quad \text{or} \quad L(\rho) = |\rho|^{1+\phi} + \psi|\rho|$$

where the additional term  $\psi|\rho|$  models proportional costs such as the bid-ask spread.

The initial A-Ch models correspond to a quadratic function  $L(\rho) = \eta\rho^2$ .

## Why should permanent market impact be linear?

Let assume that the permanent market impact is modeled by the function  $\mathcal{I}(\cdot)$ .

The dynamics of  $(q_t, S_t, X_t)$  is

$$\begin{cases} dq_t = v_t dt \\ dS_t = \sigma dW_t + \mathcal{I}(v_t) dt \\ dX_t = -v_t S_t dt \end{cases}$$

There is a dynamic arbitrage if there exist  $t_1 < t_2$ , and a process  $(v_t)_t$  such that the following conditions are satisfied:

- $\int_{t_1}^{t_2} v_t dt = 0$ ,
- $\mathbb{E}[X_{t_2} | \mathcal{F}_{t_1}] > X_{t_1}$ .

In other words, a dynamic arbitrage corresponds to a round trip strategy on the stock that is profitable on average.

## Linear permanent market impact guarantees no dynamic arbitrage.

- There is no dynamic arbitrage iff  $\mathcal{I}(\cdot)$  is a linear function.

We choose  $\mathcal{I}(v) = kv$  with  $k \geq 0$ .

- The permanent component of market impact can also depend on the number of shares already traded. For instance, a model where the price dynamics is

$$dS_t = \sigma dW_t + f(|q_0 - q_t|) v_t dt$$

with  $f$  a positive function (usually decreasing), does not lead to any dynamic arbitrage.



## Optimization problem

- Our goal is to find an optimal strategy  $(v_t)_t \in \mathcal{A}$  to liquidate the portfolio.
- Mean-variance criterion: maximize  $\mathbb{E}[X_T] - \frac{\gamma}{2}\mathbb{V}[X_T]$
- We consider an expected utility criterion. The utility function we consider is a CARA (Constant Absolute Risk Aversion) utility function, that is, an exponential utility function.
- Our objective function is of the form  $\mathbb{E}[-\exp(-\gamma X_T)]$
- $\gamma$  - absolute risk aversion coefficient

## Deterministic strategies

- We restrict liquidation strategies to deterministic ones  $\mathcal{A}_{\text{det}} \subset \mathcal{A}$ .

$$dS_t = \sigma dW_t + kv_t dt$$

$$dX_t = -v_t S_t dt - V_t L \left( \frac{v_t}{V_t} \right) dt$$

- The final value of the cash account process is given by

$$\begin{aligned} X_T &= X_0 - \int_0^T v_t S_t dt - \int_0^T V_t L \left( \frac{v_t}{V_t} \right) dt \\ &= X_0 + q_0 S_0 + \int_0^T kv_t q_t dt + \sigma \int_0^T q_t dW_t - \int_0^T V_t L \left( \frac{v_t}{V_t} \right) dt \\ &= X_0 + q_0 S_0 - \frac{k}{2} q_0^2 + \sigma \int_0^T q_t dW_t - \int_0^T V_t L \left( \frac{v_t}{V_t} \right) dt \end{aligned}$$

## Deterministic strategies

$$X_T = X_0 + q_0 S_0 - \frac{k}{2} q_0^2 + \sigma \int_0^T q_t dW_t - \int_0^T v_t L \left( \frac{v_t}{V_t} \right) dt$$

If  $(v_t)_{t \in [0, T]} \in \mathcal{A}_{\text{det}}$ , then  $X_T$  is normally distributed with mean

$$\mathbb{E}[X_T] = X_0 + q_0 S_0 - \frac{k}{2} q_0^2 - \int_0^T v_t L \left( \frac{v_t}{V_t} \right) dt,$$

and variance

$$\mathbb{V}[X_T] = \sigma^2 \int_0^T q_t^2 dt.$$

The mean of  $X_T$  can be decomposed into three parts:

$$\mathbb{E}[X_T] = \underbrace{X_0 + q_0 S_0}_{\text{MtM value}} - \underbrace{\frac{k}{2} q_0^2}_{\text{perm. m. i.}} - \underbrace{\int_0^T v_t L \left( \frac{v_t}{V_t} \right) dt}_{\text{execution costs}}$$

## Moment-generating function - two sided Laplace transform of density

Let  $X \sim \mathcal{N}(\mu, \sigma^2)$  and  $\gamma > 0$ . Then

$$\mathbb{E}[-\exp(-\gamma X)] = -\exp\left(-\gamma\mu + \frac{1}{2}\gamma^2\sigma^2\right)$$

Using moment-generating function of a Gaussian variable, we can compute the value of the objective function:

$$\begin{aligned}\mathbb{E}[-\exp(-\gamma X_T)] &= -\exp\left(-\gamma\mathbb{E}[X_T] + \frac{1}{2}\gamma^2\mathbb{V}[X_T]\right) \\ &= -\exp\left(-\gamma\left(X_0 + q_0 S_0 - \frac{k}{2}q_0^2\right)\right) \\ &\times \exp\left(\gamma\left(\int_0^T V_t L\left(\frac{V_t}{V_t}\right) dt + \frac{\gamma}{2}\sigma^2 \int_0^T q_t^2 dt\right)\right).\end{aligned}$$

## Optimisation problem

As a consequence the problem boils down to finding a control process  $(v_t)_{t \in [0, T]} \in \mathcal{A}_{\text{det}}$  minimizing

$$\int_0^T v_t L \left( \frac{v_t}{V_t} \right) dt + \frac{\gamma}{2} \sigma^2 \int_0^T q_t^2 dt.$$

Because  $v_t = \frac{dq_t}{dt}$ , the problem boils down to a variational problem (Bolza problem). We need to find minimizers of the functional  $J$  defined by

$$J(q) = \int_0^T \left( v_t L \left( \frac{q'(t)}{V_t} \right) + \frac{1}{2} \gamma \sigma^2 q(t)^2 \right) dt$$

over the set of absolutely continuous functions  $q$  satisfying the constraints  $q(0) = q_0$  and  $q(T) = 0$ . (There exists a unique minimizer  $q^*$ -nonincreasing.)

## Characterisation of the optimal strategy

To characterize the optimal strategy  $q^*$  we can use an Euler-Lagrange characterization.

$$F(q) = \int_a^b f(t, q(t), q'(t)) dt, \quad f(\cdot) = f(t, x, v)$$
$$f_x(t, q(t), q'(t)) = \frac{d}{dt} f_v(t, q(t), q'(t))$$

If  $L$  is differentiable then the Euler-Lagrange equation reduces to

$$\begin{cases} p'(t) = \gamma \sigma^2 q^*(t) \\ p(t) = L' \left( \frac{q^*(t)}{V_t} \right) \\ q^*(0) = q_0 \\ q^*(T) = 0. \end{cases}$$



## Legendre Fenchel transform

Let  $H$  be the Legendre-Fenchel transform of the function  $L$  defined by

$$H(p) = \sup_{\rho} (\rho p - L(\rho)).$$

Because  $L$  is strictly convex,  $H$  is a function of class  $C^1$ .

We know that  $p(t) = L' \left( \frac{q^*(t)}{V_t} \right)$  and the L-F transform can be specified by the condition

$$H' = (L')^{-1}$$

Then we get a characterization of the E-L system by the Hamiltonian system:

$$\begin{cases} p'(t) = \gamma \sigma^2 q^*(t) \\ q^{*'}(t) = V(t) H'(p(t)) \\ q^*(0) = q_0 \\ q^*(T) = 0 \end{cases}$$

## The case of quadratic execution costs

In general the solution is given by:  $p''(t) = \gamma\sigma^2 V_t H'(p(t))$

We can prove that in our model the optimal deterministic strategy is the best in class of all (deterministic/stochastic) admissible controls. (see *Guéant's* book)

Let us take  $L(\rho) = \eta\rho^2$ . Using the characterisation  $H' = (L')^{-1}$ , the associated Hamiltonian function is  $H(p) = \frac{p^2}{4\eta}$ .

$$\begin{cases} p'(t) = \gamma\sigma^2 q^*(t), \\ q^{*'}(t) = V_t H'(p) = \frac{V_t}{2\eta} p(t), \\ q^*(0) = q_0, \\ q^*(T) = 0. \end{cases}$$

Consequently,  $q^*$  is the unique solution of the equation

$$q^{*''}(t) = \frac{\gamma\sigma^2 V_t}{2\eta} q^*(t),$$

satisfying the boundary conditions  $q^*(0) = q_0$  and  $q^*(T) = 0$ .

## Classical Almgren-Chriss formula

If  $(V_t)_t$  is assumed to be constant (i.e.  $V_t = V, \forall t \in [0, T]$ ), then we get the classical hyperbolic sine formula of Almgren and Chriss:

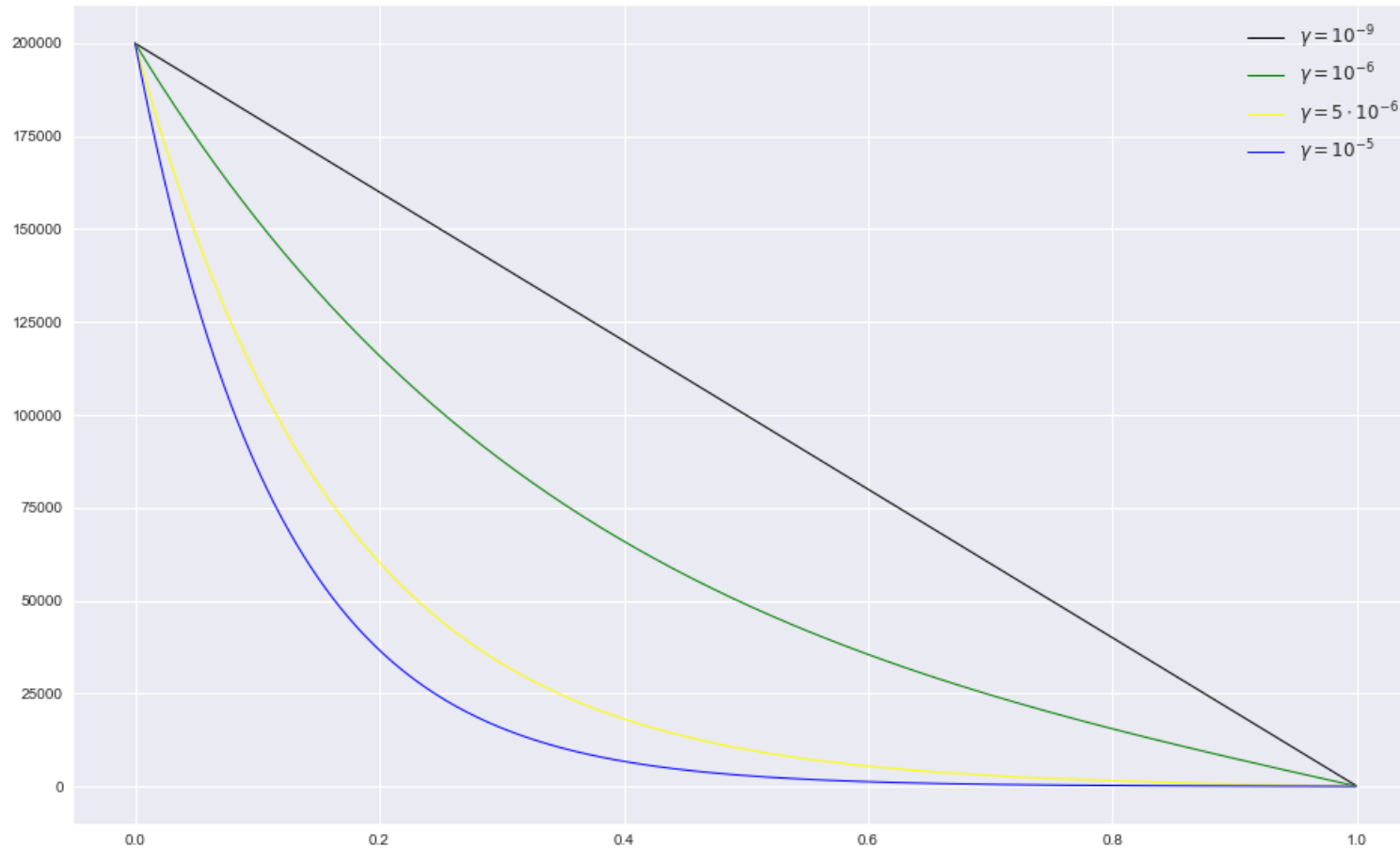
$$q^*(t) = q_0 \frac{\sinh\left(\sqrt{\frac{\gamma\sigma^2 V}{2\eta}}(T-t)\right)}{\sinh\left(\sqrt{\frac{\gamma\sigma^2 V}{2\eta}}T\right)}$$

Associated to this optimal trading curve, the optimal (deterministic) strategy  $(v_t^*)_t$  is given by

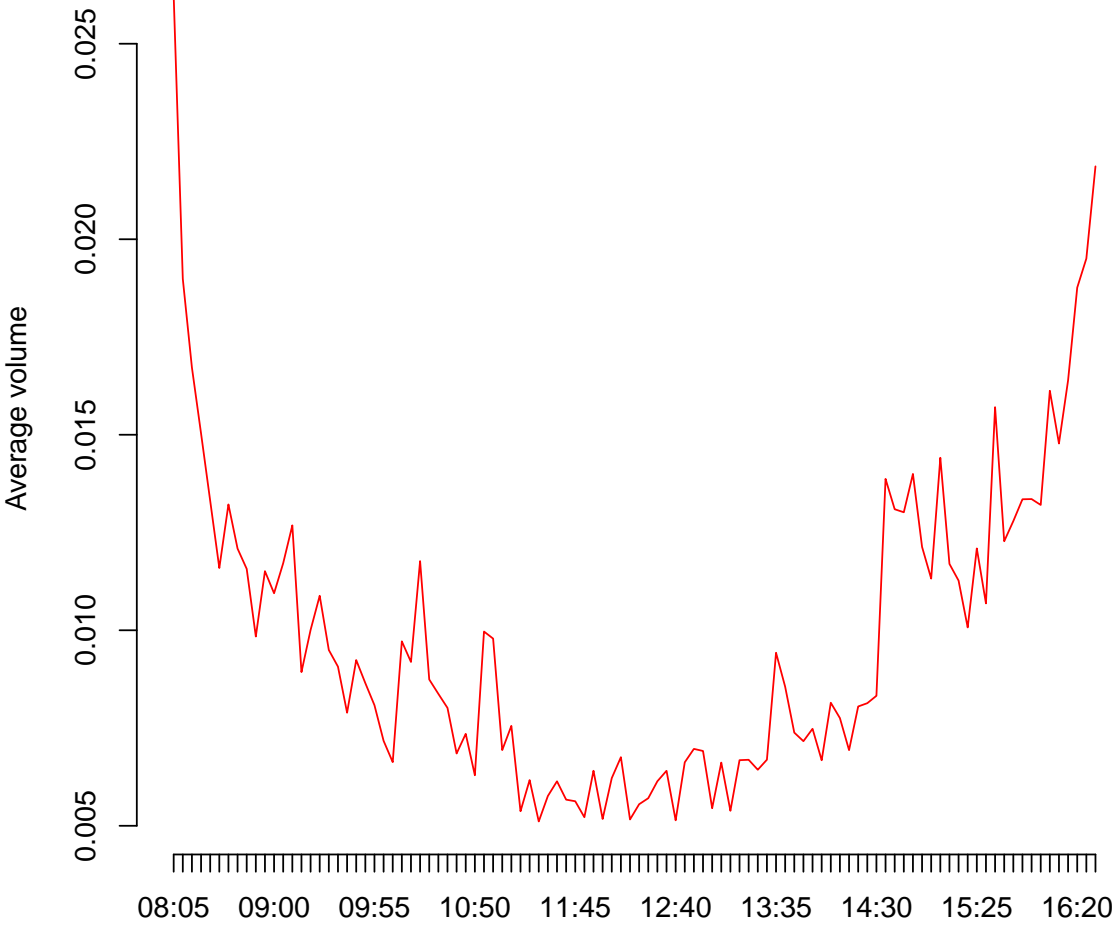
$$v_t^* = q^{*'}(t) = -q_0 \sqrt{\frac{\gamma\sigma^2 V}{2\eta}} \frac{\cosh\left(\sqrt{\frac{\gamma\sigma^2 V}{2\eta}}(T-t)\right)}{\sinh\left(\sqrt{\frac{\gamma\sigma^2 V}{2\eta}}T\right)}.$$

# Optimal trading curves for different $\gamma$ parameters

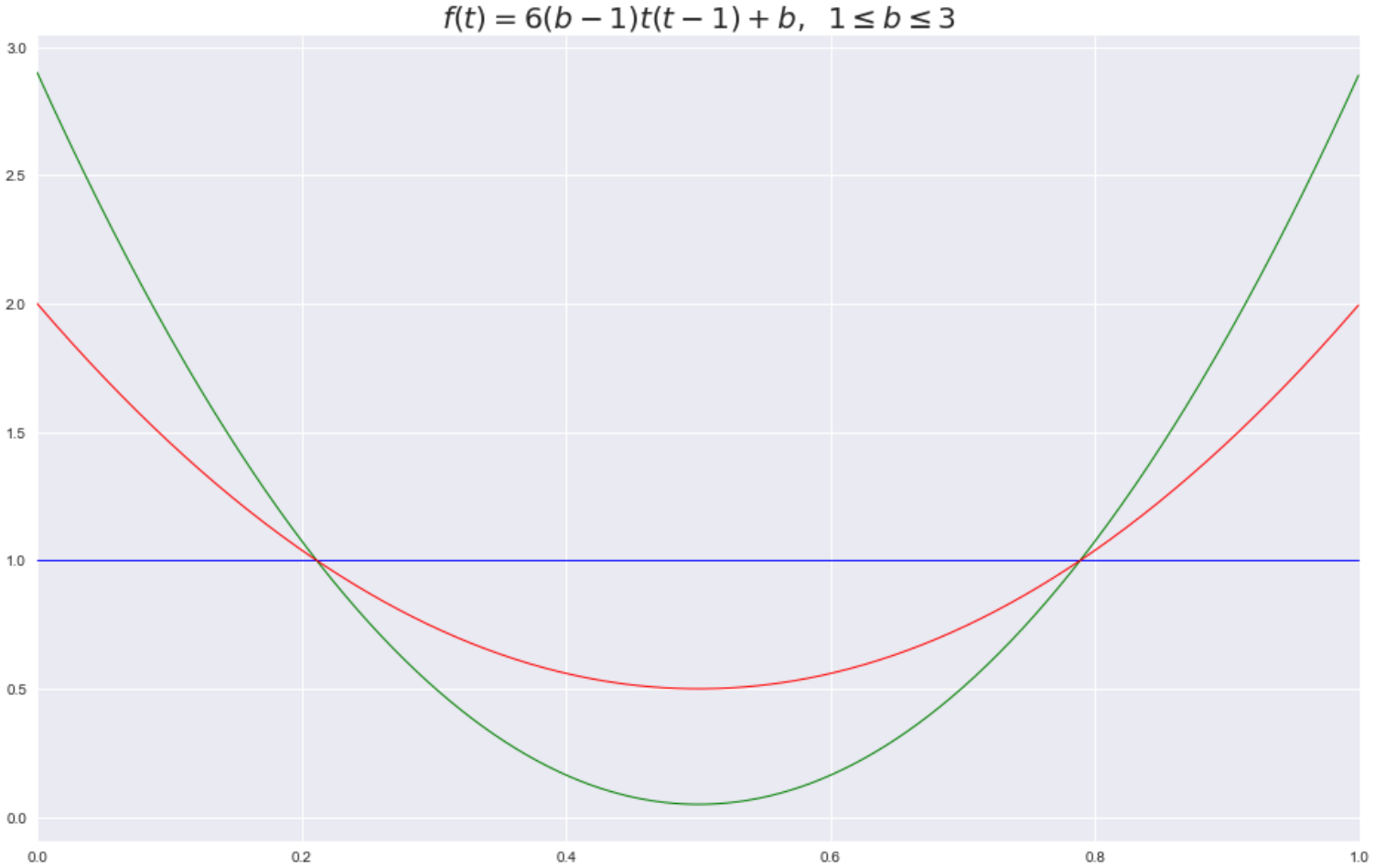
$S_0 = 45 \text{ €}$ ,  $\sigma = 0.6 \cdot \text{day}^{-\frac{1}{2}} \cdot \text{share}^{-1}$  (annual volatility 21%),  $q_0 = 200,000$  shares  
 $V = 4,000,000 \text{ shares} \cdot \text{day}^{-1}$ ,  $\eta = 0.1 \text{ €} \cdot \text{share}^{-1}$ ,  $T = 1$  (day)



# Normalised average volume for BNP Paribas aggregated in 5 min bins



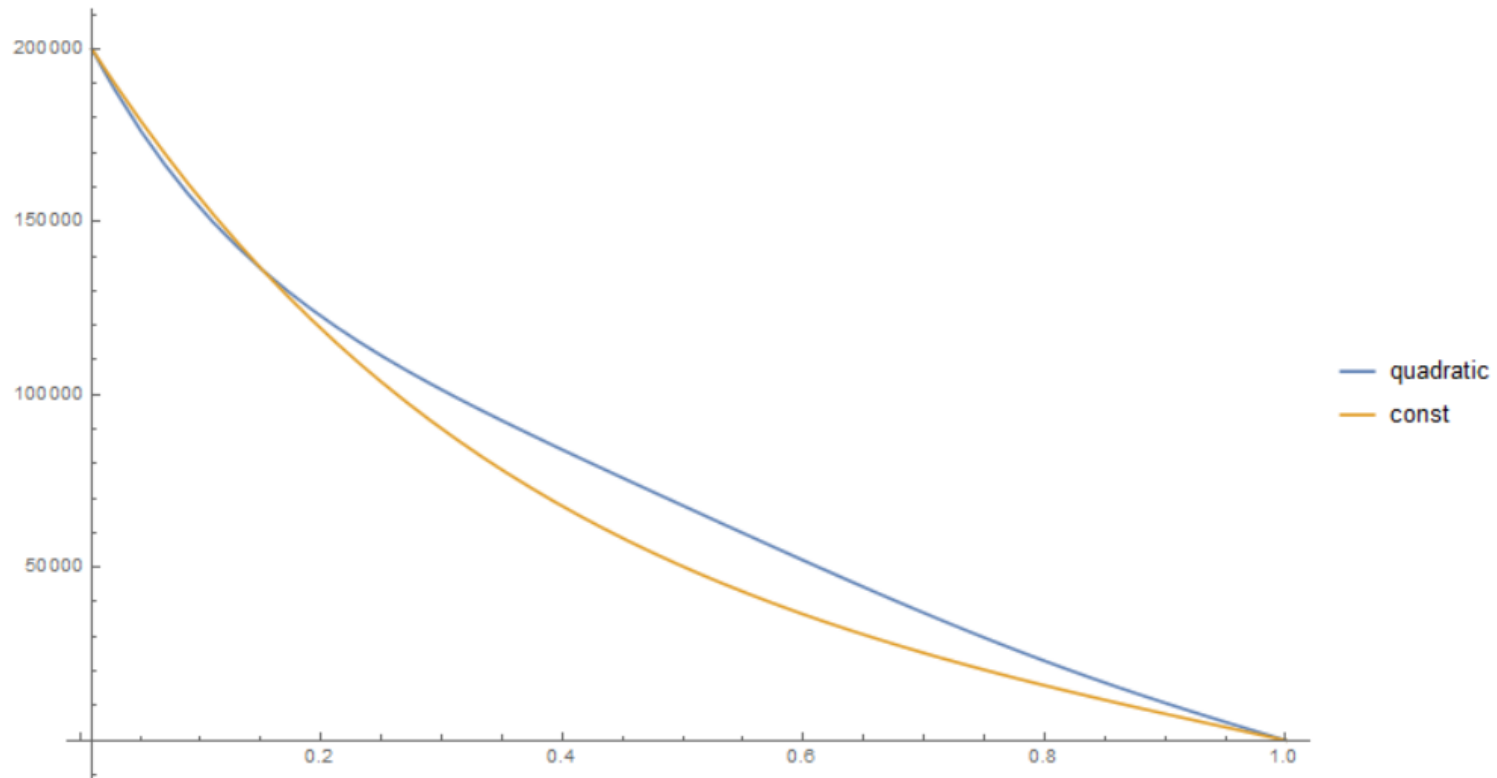
# Constant vs quadratic $V_t = V \cdot f(t)$





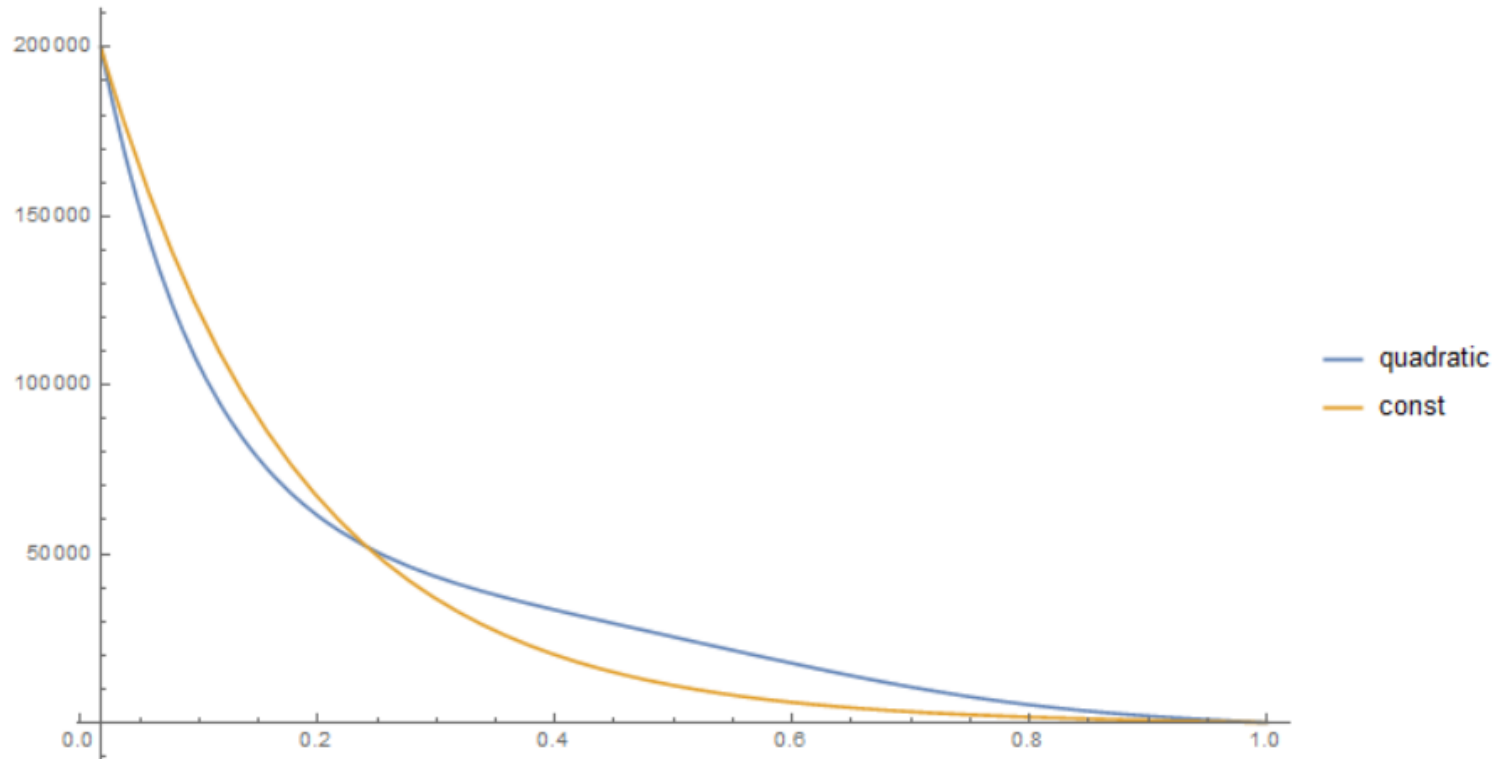
# Constant vs quadratic $V_t$

$q_0 = 200,000$ ,  $V = 4,000,000$ ,  $\sigma = 0.6$ ,  $\eta = 0.1$ ,  $\gamma = 10^{-6}$ ,  $b = 2.9$ ,  $T = 1$



# Constant vs quadratic $V_t$

$q_0 = 200,000$ ,  $V = 40,000,000$ ,  $\sigma = 0.6$ ,  $\eta = 0.1$ ,  $\gamma = 10^{-6}$ ,  $b = 2.999$ ,  $T = 1$



## Extensions of the Almgren-Chriss framework

- Optimisation of different benchmark orders, e.g. optimal participation rate for POV, target close algo,
- Different dynamics, e.g.  $dS_t = \mu_t dt + \sigma_t dW_t + kv_t dt$  with  $\mu_t, \sigma_t$ -deterministic,
- Model with constraints, e.g. minimal participation rate,
- Portfolio liquidation,
- Different liquidity costs  $L(\rho) = |\rho|^{1+\phi} + \psi|\rho|$ .

# Bibliography

[1] Olivier GUÉANT, *The Financial Mathematics of Market Liquidity*, 2016.

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Q & A

